ON ALLEE EFFECTS IN STRUCTURED POPULATIONS

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Abstract. Maps \( f(x) = A(x)x \) of the non-negative cone \( C \) of \( \mathbb{R}^k \) into itself are considered where \( A(x) \) are non-negative, primitive matrices with non-decreasing entries and at least one increasing entry. Let \( \lambda(x) \) denote the dominant eigenvalue of \( A(x) \) and \( \lambda(\infty) = \sup_{x \in C} \lambda(x) \). These maps are shown to exhibit a dynamical trichotomy. First, if \( \lambda(0) \geq 1 \), then \( \lim_{n \to \infty} \| f^n(x) \| = \infty \) for all non-zero \( x \in C \). Second, if \( \lambda(\infty) \leq 1 \), then \( \lim_{n \to \infty} f^n(x) = 0 \) for all \( x \in C \). Finally, if \( \lambda(0) < 1 \) and \( \lambda(\infty) > 1 \), then there exists a compact invariant hypersurface \( \Gamma \) separating \( C \). For \( x \) below \( \Gamma \), \( \lim_{n \to \infty} f^n(x) = 0 \), while for \( x \) above, \( \lim_{n \to \infty} \| f^n(x) \| = \infty \). An application to non-linear Leslie matrices is given.

1. Introduction

Difference equation models for single species population dynamics are of the form
\[
(x') = a(x)x
\] (1)
where \( x \) is a non-negative real representing the current population density, \( a(x) \) is the per-capita growth rate of the population, and \( x' \) is the population density in the next generation. When resources are abundant, the per-capita growth rate \( a(x) \) can be an increasing function due to predator saturation, antipredator vigilance or aggression, cooperative predation or resource defense, increased availability of mates, and conspecific enhancement of reproduction [3, 8, 9]. For example, Hassell [4] in modeling a population subject to predation by a satiating generalist uses \( a(x) = \lambda \exp(-\alpha/(1 + \beta x)) \) where \( \lambda \) is the geometric growth rate of the population in the absence of predation, \( \alpha \) determines the maximum predation rate, and \( \beta \) determine how quickly the predators satiate. Models of this type are easily seen to exhibit a trichotomy of dynamical behaviors:
- If \( a(0) \geq 1 \), then \( \lim_{n \to \infty} f^n(x) = \infty \) for all \( x > 0 \).
- If \( \lim_{x \to \infty} a(x) \leq 1 \), then \( \lim_{n \to \infty} f^n(x) = 0 \) for all \( x \geq 0 \).
- If \( \lim_{x \to \infty} a(x) > 1 \) (possibly infinite) and \( a(0) < 1 \), then there exists a positive equilibrium \( x^* \) such that \( \lim_{n \to \infty} f^n(x) = 0 \) for all \( x < x^* \) and \( \lim_{n \to \infty} f^n(x) = \infty \) for all \( x > x^* \).

The last of these dynamical behaviors corresponds to what is known as a (strong) Allee effect– there exists a critical density below which extinction is inevitable [8].

The goal of this article is to extend the dynamical trichotomy from one-dimensional maps for unstructured populations to \( k \)-dimensional maps for structured populations (i.e. populations divided up into subpopulation via age, stage, or space).

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The remainder of the article is structured as follows. In section 2, we present the multidimensional analogs of (1), introduce basic definitions, and state the main result. The main result is proven in section 3 and an application to age-structured populations is given in section 4.

2. Main result

Let \( C \) denote the non-negative cone of \( \mathbb{R}^k \). Given \( x = (x_1, \ldots, x_k) \) and \( y = (y_1, \ldots, y_k) \) in \( C \), we write \( x \leq y \) if \( x_i \leq y_i \) for all \( i \), \( x < y \) if \( x \leq y \) and \( x \neq y \), and \( x \ll y \) if \( x_i < y_i \) for all \( i \). Given two \( k \times k \) matrices, \( A \) and \( B \), whose \( i-j \)-th entries are given by \( a_{ij} \) and \( b_{ij} \), we write \( A \leq B \) if \( a_{ij} \leq b_{ij} \) for all \( i \) and \( j \), \( A < B \) if \( A \leq B \) and \( A \neq B \), and \( A \ll B \) if \( a_{ij} < b_{ij} \) for all \( i \) and \( j \). Let \( f : C \to C \) be given by

\[
f(x) = A(x)x
\]

where \( A(x) \) are \( k \times k \) non-negative matrices whose \( i-j \)-th entry are given by \( a_{ij}(x) \). About \( A(x) \) we make the following standing assumptions

- **A1**: \( A(0) \) is primitive (i.e. there exists a positive integer \( n \) such that all the entries of \( A(0)^n \) are positive),
- **A2**: \( x \mapsto A(x) \) is continuously differentiable,
- **A3**: \( A(x) \leq A(y) \) whenever \( x \leq y \), and
- **A4**: there exist \( i,j,l \) such that for all \( x \in C \), \( \frac{\partial a_{ij}}{\partial x_l}(x) > 0 \).

Define the limiting matrix \( A(\infty) \) with entries \( a_{ij}(\infty) \) by

\[
a_{ij}(\infty) = \sup_{x \in C} a_{ij}(x).
\]

Some of the entries of this matrix may be \( \infty \). Assumptions **A1** and **A3** imply that \( A(x) \) is primitive for all \( x \in C \). Hence (see, e.g., [7]), there exists a dominant eigenvalue \( \lambda(\infty) > 0 \). Define \( \lambda(\infty) \) to be the dominant eigenvalue of \( A(\infty) \) if all the entries of \( A(\infty) \) are finite and \( \infty \) otherwise. Given a point \( x \in C \), let

\[
\|x\| = \max\{x_1, \ldots, x_k\} \quad \min(x) = \min\{x_1, \ldots, x_k\}.
\]

Our main result is as follows:

**Theorem 1.** \( f(x) \) has three possible dynamics:

1. If \( \lambda(\infty) \leq 1 \), then \( \lim_{n \to \infty} f^n(x) = 0 \) for any \( x \in C \).
2. If \( \lambda(0) \geq 1 \), then \( \lim_{n \to \infty} \min(f^n(x)) = \infty \) for any non-zero \( x \in C \).
3. If \( \lambda(0) < 1 \) and \( \lambda(\infty) > 1 \), then there exists a continuously differentiable invariant hypersurface \( \Gamma \) that separates \( C \) into two pieces. For points \( x \) below \( \Gamma \) (i.e. \( x \) such that \( x < y \) for some \( y \in \Gamma \)),

\[
\lim_{n \to \infty} f^n(x) = 0
\]

Alternatively, for points \( x \) above \( \Gamma \) (i.e. \( x \) such that \( x > y \) for some \( y \in \Gamma \)),

\[
\lim_{n \to \infty} \min(f^n(x)) = \infty.
\]

**Remark.** A similar result can be proven for ordinary differential equations of the form \( \frac{dx}{dt} = A(x)x \) where \( A(x) \) are \( k \times k \) matrices (not necessarily non-negative), \( \exp(A(0)) \) is primitive, and assumptions **A2**–**A4** hold.
3. Proof of Main Result

The proof of Thm. 1 relies heavily on the fact that \( f(x) \) is a monotone map (i.e. \( f(x) \geq f(y) \) whenever \( x \geq y \)). In fact, the following lemma implies that there exists a positive integer \( N \) such that \( f^N(x) \) is strongly monotone (i.e. \( f^N(x) \gg f^N(y) \) whenever \( x > y \)).

**Lemma 1.** \( A(x) \) has the following properties

1. There exists a positive integer \( N \) such that the entries of \( A(0)^N \) are all positive and \( A(0)^N \gg A(y)^N \) whenever \( x > y \).
2. \( \lambda(x) \geq \lambda(y) \) whenever \( x \geq y \).
3. \( \lambda(x) > \lambda(y) \) whenever \( x > y \).

**Proof.** Since \( A(0) \) is primitive, there exists a positive integer \( L \) such that all the entries of \( A(0)^L \) are positive. Set \( N = 3L \). To see why this gives the desired \( N \), assume \( x > y \). Assumptions \( A3 \) and \( A4 \) imply that \( A(x)^L > A(y)^L > A(0)^L \). In particular, all the entries of \( A(y)^L \) are positive and one of the entries of \( A(x)^L \) is greater than the corresponding entry of \( A(y)^L \). It follows that all the entries of a row and a column of \( A(x)^{2L} \) are greater than the corresponding entries of \( A(y)^{2L} \). Iterating one more time yields that \( A(x)^{3L} \gg A(y)^{3L} \).

Assume \( x \geq y \). Since \( A(x) \geq A(y) \),

\[
\lambda(x) = \lim_{n \to \infty} \|A(x)^n\|^{1/n} \geq \lim_{n \to \infty} \|A(y)^n\|^{1/n} = \lambda(y).
\]

Assume \( x < y \). Since \( A(x)^N \gg A(y)^N \), there exists an \( \epsilon > 0 \) such that \( A(x)^N \geq (1 + \epsilon)^N A(y)^N \). Thus \( \lambda(x) \geq (1 + \epsilon)\lambda(y) \).

Assume \( \lambda(\infty) \leq 1 \). Choose an \( x \in C \). Since \( \lambda(\infty) \leq 1 \) and \( A(\infty) \) is primitive, the Perron-Frobenius Theorem (see, e.g., [7]) implies that there exists a constant \( c \geq 1 \) such that \( \|A(\infty)^n\| \leq c \) for all \( n \geq 0 \). Since \( A(y) \leq A(\infty) \) for all \( y \in C \),

\[
\|f^n(x)\| = \|A(f^{n-1}(x)) \ldots A(x)x\| \leq \|A(\infty)^n x\| \leq c\|x\|
\]

for all \( n \geq 0 \). Let \( z = c\|x\|(1,1, \ldots, 1) \). Lemma 1 implies that \( \lambda(z) < \lambda(\infty) \leq 1 \).

Since \( f^n(x) \leq z \) for all \( n \geq 0 \), we have that \( A(f^n(x)) \leq A(z) \) for all \( n \geq 0 \). The Perron-Frobenius Theorem implies that \( \lim_{n \to \infty} \|A(z)^n v\|^{1/n} = \lambda(z) \) for all \( v \in C \). Therefore,

\[
\lim_{n \to \infty} \sup_{n \to \infty} \|f^n(x)\|^{1/n} = \lim_{n \to \infty} \sup_{n \to \infty} \|A(f^{n-1}(x)) \ldots A(x)x\|^{1/n} \leq \lambda(z) < 1.
\]

In particular, \( \lim_{n \to \infty} f^n(x) = 0 \).

Next, assume \( \lambda(0) \geq 1 \). Choose a non-zero \( x \in C \). Since \( \lambda(0) \geq 1 \) and \( A(0) \) is primitive, the Perron-Frobenius Theorem implies that there exists a constant \( c > 0 \) such that \( A(0)^n x \geq c x \) for all \( n \geq N \). Since \( A(y) \geq A(0) \) for all \( y \in C \),

\[
f^n(x) = A(f^{n-1}(x)) \ldots A(x)x \geq A(0)^n x \geq c x
\]

for all \( n \geq N \). By Lemma 1, \( \lambda(c x) > \lambda(0) \geq 1 \). Since \( f^n(x) \geq c x \) for all \( n \geq N \), \( A(f^n(x)) \geq A(c x) \) for all \( n \geq N \). The Perron-Frobenius Theorem implies that \( \lim_{n \to \infty} \min_{n \to \infty} (A(c x)^n v)^{1/n} = \lambda(c x) \) for all \( v \in C \). Hence

\[
\lim_{n \to \infty} \min_{n \to \infty} (f^n(x))^{1/n} = \lim_{n \to \infty} \min_{n \to \infty} (A(f^{n-1} x) \ldots A(x)x)^{1/n} \geq \lambda(c x) > 1.
\]

In particular, \( \lim_{n \to \infty} \min_{n \to \infty} (f^n(x)) = \infty \).
Finally, assume that \( \lambda(\infty) > 1 \) and \( \lambda(0) < 1 \). Since \( \lambda(0) < 1 \), \( 0 \) is an attracting fixed point with an open \emph{basin of attraction}:

\[
\mathcal{B}(0) = \{ x \in C : \lim_{n \to \infty} f^n(x) = 0 \}
\]

On the other hand, the following lemma implies that \( \mathcal{B}(0) \) is bounded.

**Lemma 2.** Assume \( \lambda(0) < 1 \) and \( \lambda(\infty) > 1 \). Then there exists an \( M > 0 \) such that

\[
\lim_{n \to \infty} \min(f^n(x)) = \infty
\]

whenever \( \|x\| \geq M \).

**Proof.** The definition of \( \lambda(\infty) \) and the assumption that \( \lambda(\infty) > 1 \) imply that there exists an \( M_1 \) such that \( \lambda(x) > 1 \) whenever \( \min(x) \geq M_1 \). Let \( z = M_1(1, \ldots, 1) \). Since \( \lambda(z) > 1 \), the Perron-Frobenius Theorem implies that there exists an \( \epsilon > 0 \) and \( L > 0 \) such that \( A^n(z)x \geq (1 + \epsilon)^nx \) whenever \( x \in C \) and \( n \geq L \). Choose \( 1 > \delta > 0 \) such that all entries of \( A(0)^N \) are greater than \( \delta \) and the maximum entry of each row in \( A(0) \) is greater than \( \delta \) (Note: \( A(0) \) being primitive implies that no row vector of \( A(0) \) is the zero vector). Define \( M = \frac{M_1}{\delta^L} \). Let \( x \in C \) be such that \( \|x\| \geq M \). Our choice \( x \) and \( \delta \) imply that for \( i = 0, 1, \ldots, L \)

\[
f^{N+i}(x) = A(f^{N+i-1}(x)) \ldots A(x) \\
\geq A(0)^{N+i}x \geq \|x\|^{\delta^{i+1}}(1, \ldots, 1) \\
\geq \frac{M_1}{\delta^{L-i}}(1, \ldots, 1) \geq M_1(1, \ldots, 1) = z
\]

Thus, we may inductively conclude that

\[
f^{n+N}(x) \geq (1 + \epsilon)^nz
\]

for \( n \geq L \). In particular \( \lim_{n \to \infty} \min(f^n(x)) = \infty \).

The boundary \( \partial \mathcal{B}(0) \) of \( \mathcal{B}(0) \) is a non-empty compact invariant set for \( f \). Consequently, work of Takáč [10, Prop. 1.3] implies that there exists an invariant Lipschitz hypersurface \( \Gamma \) containing \( \partial \mathcal{B}(0) \) that separates \( C \) into two pieces. In fact, work of Tereščák [11] implies that \( \Gamma \) is a continuously differentiable manifold (see also [1] in which this result is proven in the finite dimensional case when \( f \) is \( C^2 \)).

Next, we prove that \( \Gamma \) is a \emph{repeller}: there exists a neighborhood \( U \) of \( \Gamma \) such that for all \( x \in U \setminus \Gamma \), \( f^n(x) \notin U \) for all \( n \) sufficiently large. Since \( \Gamma \) is compact and does not contain the origin, there exists a constant \( c > 0 \) such that \( c(1, 1, \ldots, 1) \gg x \gg (1, 1, \ldots, 1)/c \) for all \( x \in \Gamma \). Since \( \lim_{n \to \infty} c^{1/n} = 1 \) and \( \Gamma \) is invariant,

\[
\lim_{n \to \infty} \|A(f^{n-1}(x)) \ldots A(x)x\|^{1/n} = \lim_{n \to \infty} \|f^n(x)\|^{1/n} = 1
\]

for all \( x \in \Gamma \). We need the following result of Ruelle.
Proposition 1. [5, Prop. 3.2] Let $X$ be a compact metric space, $f : X \to X$ a continuous map, and $T$ a continuous map from $X$ to the space of $k \times k$ non-negative primitive matrices. Then there exists a continuous $T$-invariant splitting $E \oplus F$ of $X \times \mathbb{R}^k$ and constants $\alpha < 1$ and $K \geq 0$ such that for all $x \in X$

\begin{itemize}
\item $F(x)$ is one-dimensional and contained in $\mathcal{C} = \{ y \in \mathbb{R}^k : y \gg 0 \text{ or } y \ll 0 \}$
\item $E(x) \setminus \{ 0 \}$ is contained in the interior of the the complement of $\mathcal{C}$, and
\item for all unit vectors $v \in E(x)$ and $w \in F(x)$,
\end{itemize}

$$\|T(f^{n-1}(x)) \ldots T(x)v\| \leq K\alpha^n\|T(f^{n-1}(x)) \ldots T(x)w\|$$

Ruelle's result applied to $T = A$ and (2) imply

$$(3) \quad \lim_{n \to \infty} \|A(f^{n-1}(x)) \ldots A(x)v\|^{1/n} = 1$$

for all $x \in \Gamma$ and non-zero $v \in C$. By the chain rule, the derivative $Df(x)$ of $f(x)$ equals

$$Df(x) = A(x) + DA(x)x$$

$\textbf{A3}$ implies that all the entries of $DA(x)$ are non-negative. $\textbf{A4}$ implies that $DA(x)$ contains at least one positive entry for all $x \in C$. The arguments used to prove Lemma 1 imply that

$$Df^N(x) = Df(f^{N-1}(x)) \ldots Df(f(x))Df(x) \gg A(f^{N-1}(x)) \ldots A(f(x))A(x).$$

Compactness and invariance of $\Gamma$ imply that there exists an $\epsilon > 0$ such that

$$Df^n(x) \geq (1 + \epsilon)^nA(f^{n-1}(x)) \ldots A(f(x))A(x)$$

for all $x \in \Gamma$ and $n \geq N$. Equation (3) implies

$$(4) \quad \lim_{n \to \infty} \inf \|Df^n(x)v\|^{1/n} \geq 1 + \epsilon$$

for all $x \in \Gamma$ and non-zero $v \in C$. Prop. 1 applied to $T = Df$ and $X = \Gamma$ yields a $Df$ invariant splitting $E \oplus F$ in which $E$ is the tangent bundle to $\Gamma$ and $F$ is a one dimensional vector bundle transverse to $\Gamma$. Equation (4) and the following theorem

Theorem 2. [6, Thm. 1] Let $f : X \to X$ be a continuous map of a compact metric space $X$. If $F_n : X \to \mathbb{R}$ is a sequence of continuous and subadditive functions (i.e. $F_{n+m}(x) \leq F_n(x) + F_m(f^n(x))$ for all $n, m \geq 1$ and $x \in \Gamma$), then

$$\sup_{x \in \Gamma} \limsup_{n \to \infty} \frac{F_n(x)}{n} = \inf_{n \geq 1} \sup_{x \in \Gamma} F_n(x)$$

applied to $X = \Gamma$, $F_n(x) = -\ln\|Df^L(x)v\|$ imply that there exists $L > 0$ such that

$$\|Df^L(x)v\| \geq (1 + \epsilon/2)^L\|v\| \quad \text{for } v \in F(x), x \in \Gamma.$$
factor $(1 + \delta)$ larger than the corresponding entry of $A(f^n y)$. The arguments used to prove Lemma 1 imply there exists an $\epsilon > 0$ such that

$$A(f^{n+N}(x)) \ldots A(f^{n+1}(x)) \geq (1 + \epsilon)^N A(f^{n+N}(y)) \ldots A(f^{n+1}(y))$$

for all $n \geq m$. Since $y \in \Gamma$, (2) implies

$$\limsup_{n \to \infty} \min(f^n(x))^{1/n} = \limsup_{n \to \infty} (A(f^{n-1}(x)) \ldots A(x)x)^{1/n} \geq \limsup_{n \to \infty} (1 + \epsilon)\min(A(f^{n-1}(y)) \ldots A(y)x)^{1/n} = 1 + \epsilon.$$ 

In particular, $\lim_{n \to \infty} \min(f^n(x)) = \infty.$

4. Application to Age-structured Models

Consider a population that consists of $k$ distinct stages. Let $x = (x_1, \ldots, x_k)$ denote the vector of the stage densities. A standard model (known as a non-linear Leslie matrix model [2]) for this population is given by

$$A(x) = \begin{pmatrix}
0 & f_2(x) & f_3(x) & \cdots & f_{k-1}(x) & f_k(x) \\
s_1(x) & 0 & 0 & \cdots & 0 & 0 \\
0 & s_2(x) & 0 & \cdots & 0 & 0 \\
\vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & \cdots & s_{k-1}(x) & s_k(x)
\end{pmatrix}$$

where $f_i(x)$ and $s_i(x)$ are functions from $C$ to $[0, \infty)$ and $(0, 1)$ respectively. $f_i(x)$ represents the average number of progeny produced from an individual in stage $i$. $s_i(x)$ is the fraction of individuals in stage $i$ that make it to stage $i + 1$. An important quantity associated with $A(x)$ is the reproductive value $R(x)$ of a stage 1 individual:

$$R(x) = s_1(x) f_2(x) + \cdots + s_1(x) \cdots s_{k-1}(x) f_{k-1}(x) + s_1(x) \cdots s_{k-1}(x) f_k(x)/(1 - s_k(x)).$$

Corollary 1. Assume that

- $x \mapsto s_i(x)$ and $x \mapsto f_i(x)$ are continuously differentiable,
- $s_i(0) > 0$ for $1 \leq i \leq k$ and $f_i(0) > 0$ for some $i \geq 2$,
- $s_i(y) \geq s_i(x)$ and $f_i(y) \geq f_i(x)$ whenever $x \leq y$, and
- there exist $i$ and $j$ such that either $\frac{\partial s_i}{\partial y_j}(x) > 0$ for all $x \in C$ or $\frac{\partial f_i}{\partial y_j}(x) > 0$ for all $x \in C$.

Then

- If $R(0) \geq 1$, then $\lim_{n \to \infty} \min(f^n(x)) = \infty$ for all non-zero $x \in C$.
- If $R(\infty) \leq 1$, then $\lim_{n \to \infty} f^n(x) = 0$ for all $x \in C$.
- If $R(0) < 1$ and $R(\infty) > 1$, then there exists a continuously differentiable invariant hypersurface $\Gamma$ that separates $C$ into two pieces. For points $x$ below $\Gamma$,

$$\lim_{n \to \infty} f^n(x) = 0$$

Alternatively, for points $x$ above $\Gamma$,

$$\lim_{n \to \infty} \min(f^n(x)) = \infty.$$ 

Functions that satisfy the assumptions of this corollary include $s_i(x) = \exp(-b_i/(1 + \beta_i x_1 + \cdots + \beta_k x_k))$ representing the fraction of individuals in stage $i$ that escape predation from a satiating generalist predator.
Proof. The assumption of the corollary ensure that A1–A4 are satisfied. To apply Theorem 1, it suffices to show that \(\lambda(x) > 1\) (resp. \(\lambda(x) < 1\)) if and only if \(R(x) > 1\) (resp. \(R(x) < 1\)). The characteristic polynomial of \(A(x)\) is given by

\[
(-\lambda)^{k-1}(s_k - \lambda) - s_1 f_2(-\lambda)^{k-3}(s_k - \lambda) + s_1 s_2 f_3(-\lambda)^{k-4}(s_k - \lambda) + \ldots \\
+ (-1)^k s_1 s_2 \ldots s_{k-2} f_{k-1}(s_k - \lambda) + (-1)^{k+1} s_1 \ldots s_{k-1} f_k
\]

Setting this equal to zero and rearranging terms (including a division by \(s_k - \lambda\) which is permissible since the dominant eigenvalue of \(A(x)\) is \(s_k\)) yields that the dominant eigenvalue \(\lambda = \lambda(x)\) of \(A(x)\) must satisfy

\[
1 = s_1 f_2/\lambda^2 + s_1 s_2 f_3/\lambda^3 + \ldots + s_1 \ldots s_{k-2} f_{k-1}/\lambda^{k-1} \\
+ s_1 \ldots s_{k-1} f_k/(\lambda^{k-1}(\lambda - s_k))
\]

Since \(\lambda(x) > s_k\) and the right hand side of (5) is a decreasing function of \(\lambda\) for \(\lambda > s_k\), we get that \(\lambda(x) > 1\) (resp. \(\lambda(x) < 1\)) if and only if \(R(x) > 1\) (resp. \(R(x) < 1\)). □

References


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